

1. K77 Incremental Optical Encoder (Through shaft)

1.1 Introduction:

K77 is an ultra-thin through shaft design, unique flexible spring plate install, multiple electrical interfaces, protection grade up to IP65, compact, easy to install, and can meet the user's requirements of environment and limited space.

1.2 Feature:

- Encoder external diameter $\varnothing 77$ mm, thickness 31mm, diameter of shaft up to $\varnothing 30$ mm, achieve ultra-thin miniaturization;
- Ring locking mounting structure;
- Adopt non-contact photoelectric principle;
- Reverse polarity protection;
- Short circuit protection;
- Multiple electrical interfaces available;
- Resolution up to 10000PPR.

1.3 Application:

Motor, CNC and other industrial automation

1.4 Connection:

- Radial socket (M12 8pin male socket)
- Radial cable (standard length 1M)

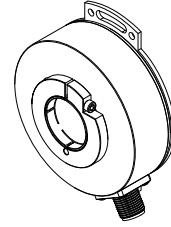
1.5 Protection:

IP65

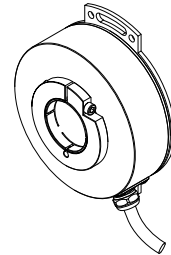
1.6 Weight:

About 400g

K77-C

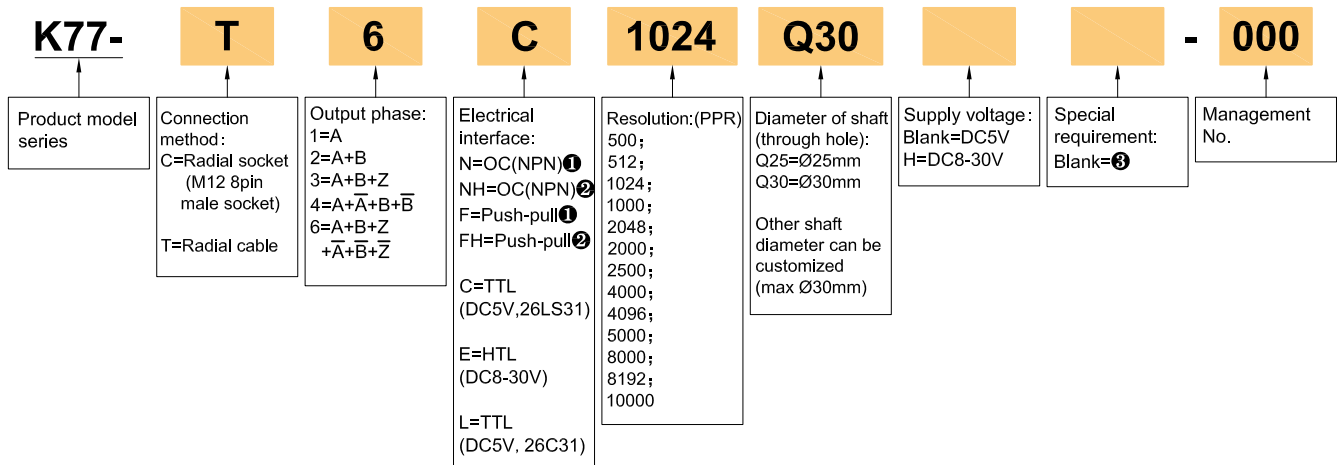


K77-T



2. Model Selection Guide

2.1 Model composition(select parameters)



2.2 Note

- Z signal is low level active.
- Z signal is high level active.
- None indicated for IP65 and cable length of 1M, if need to change the length C+number, the longest is 100M (expressed by C100). For the specific length of use, pls refer to page 2 of the provision of output circuit.

3. Output Mode

| Electrical interface | Output circuit | Output wave form |
|--|----------------|---|
| <p>OC NPN (open collector circuit)</p> | | <p>Phase A is ahead of B by $\frac{I}{4} \pm 8$, Viewing from the front of encoder, direction is counterclockwise rotation (See dimensional drawings)</p> <p>CCW direction →</p> <p>Z signal is low level active</p> |
| <p>F (Push-pull)</p> | | <p>Phase A is ahead of B by $\frac{I}{4} \pm 8$, Viewing from the front of encoder, direction is counterclockwise rotation (See dimensional drawings)</p> <p>CCW direction →</p> <p>Z signal is low level active</p> |
| <p>TTL (DC5V)</p> <p>HTL (DC8-30V)</p> | | <p>Phase A is ahead of B by $\frac{I}{4} \pm 8$, Viewing from the front of encoder, direction is counterclockwise rotation (See dimensional drawings)</p> <p>CCW direction →</p> <p>Z signal is low level active</p> |

4. Electrical Parameters

| Parameter | | Electrical Interface | OC | Push-pull | TTL | HTL |
|-----------------------------|----------------|----------------------|-------------------------------------|--------------------------|----------------------------------|-------------------------------------|
| Item | | | | | | |
| Supply voltage | | | DC+5V±5%; DC8V-30V±5% | | DC+5V±5% | DC8-30V±5% |
| Consumption current | | | 100mA Max | | 120mA Max | |
| Allowable ripple | | | ≤3%rms | | | |
| Top response frequency | | | 100KHz | | 200KHz | 300KHz |
| Output capacity | Output current | Input | ≤30mA | ≤30mA | ≤±20mA | ≤±50mA |
| | | Output | — | ≤10mA | | |
| | Output voltage | "H" | — | ≥[(Supply voltage)-2.5V] | ≥2.5V | ≥V _{CC} -3 V _{DC} |
| | | "L" | ≤0.4V | ≤0.4V(30mA) | ≤0.5V | ≤ 1V V _{DC} |
| Load voltage | | ≤DC30V | — | — | | |
| Rise & Fall time | | | Less than 2us(cable length: 2m) | | Less than 1us (Cable length: 2m) | ≤100ns |
| Insulation strength | | | AC500V 60s | | | |
| Insulation resistance | | | 10MΩ | | | |
| Mark to space ratio | | | 45% to 55% | | | |
| Reverse polarity protection | | | ✓ | | | |
| Short-circuit protection | | | — | | ✓① | |
| Phase shift between A & B | | | 90°±10° (frequency in low speed) | | | |
| | | | 90°±20° (frequency in high speed) | | | |
| Origin motion | | | Low level available | | — | |
| GND | | | not connect to encoder | | | |

- ① Short-circuit to another channel or GND permitted for max.30s. ② Phase A,B,Z are back of phase U,V,W when power on.

5. Mechanical Specifications

| | |
|-------------------|--|
| Diameter of shaft | Ø25mm; Ø30mm(stainless steel) |
| Starting torque | Less than $80 \times 10^{-3} \text{ N} \cdot \text{m}$ |
| Inertia moment | Less than $100 \times 10^{-6} \text{ kg} \cdot \text{m}^2$ |
| Shaft load | Radial 70N; Axial 50N |
| Slew speed | ≤3000 rpm |
| Shell material | Aluminium alloy |
| Weight | about 400g |

6. Environmental Specifications

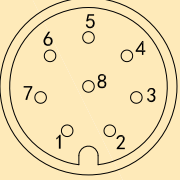
| | |
|---------------------------|---|
| Environmental temperature | Operating: -20~+85°C(repeatable winding cable: -10°C); Storage: -25~+90°C |
| Environmental humidity | Operating and storage: 35~85%RH(noncondensing) |
| Vibration(Endurance) | Amplitude 0.75mm,5~55Hz,2h for X,Y,Z direction individually |
| Shock(Endurance) | 1960m/s ² ,11ms three times for X,Y,Z direction individually |
| Protection | IP65 |

7. Wiring table

7.1 Table 1

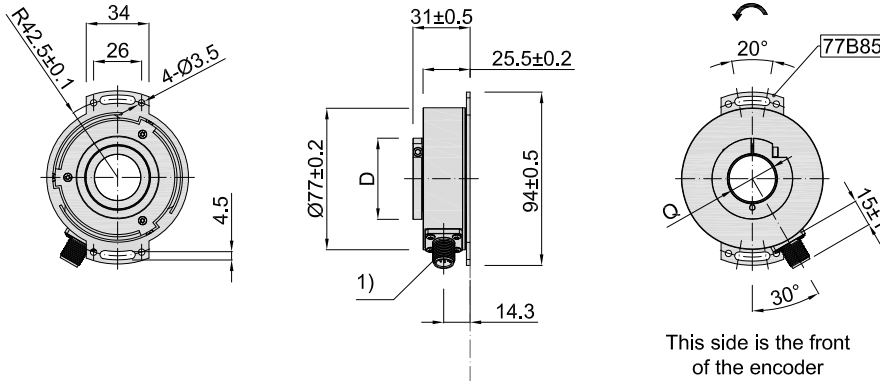
| Socket pin definition (M12 8Pin male socket) | Function | Wire color (cable connection) | Explanation | |
|---|----------|----------------------------------|-------------|-----------------------------------|
|  | 1 | Up | Red | Power supply Positive terminal |
| | 2 | Un | Black | Power supply negative terminal |
| | 3 | A | White | A (one turn pulse signal) |
| | 4 | - | - | Unallocated |
| | 5 | B | Green | B (one turn pulse signal) |
| | 6 | - | - | Unallocated |
| | 7 | Z | Yellow | Z(zero signal) |
| | 8 | - | - | Unallocated |
| | GND | GND | GND | No encoder body connected |

7.2 Table 2

| Socket pin definition (M12 8Pin male socket) | Function | Wire color (cable connection, Twisted pair) | Explanation | |
|---|----------|--|-------------|------------------------------|
|  | 1 | Up | Red | Power supply |
| | 2 | Un | Black | |
| | 3 | A | White | A (one turn pulse signal) |
| | 4 | \bar{A} | White/BK | |
| | 5 | B | Green | B (one turn pulse signal) |
| | 6 | \bar{B} | Green/BK | |
| | 7 | Z | Yellow | Z(zero signal) |
| | 8 | \bar{Z} | Yellow/BK | |
| | GND | GND | GND | GND |

8. Basic Dimensions

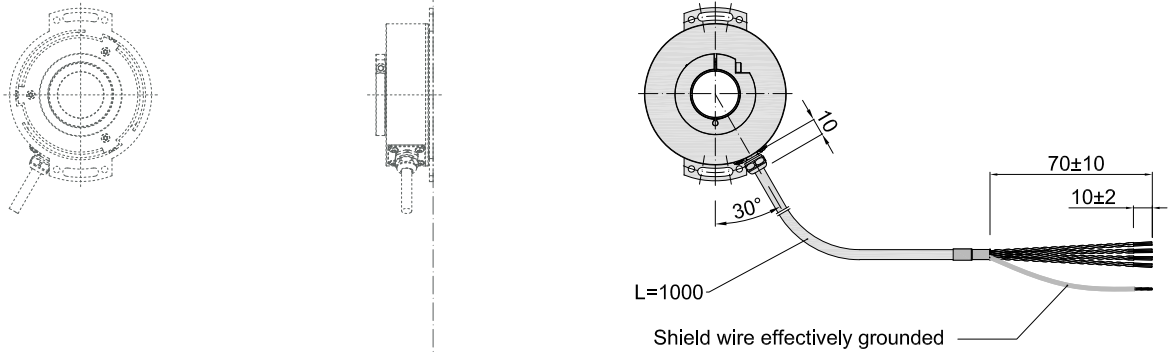
8.1 K77-C(Radial socket connection)



| Q(diameter of shaft) | D |
|----------------------------------|-----|
| Ø25 ^{G7(+0.028/+0.007)} | Ø44 |
| Ø30 ^{G7(+0.028/+0.007)} | Ø46 |

This side is the front of the encoder

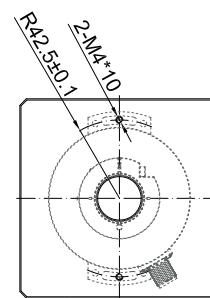
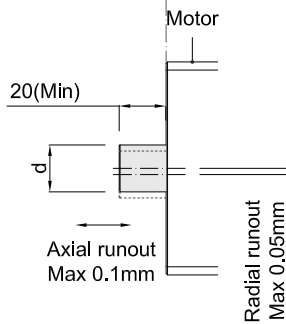
8.2 K77-T(Radial cable connection)



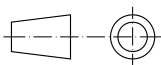
9. Assembly Requirements

| d |
|--|
| Ø25 _{g6} ^(-0.007/-0.020) |
| Ø30 _{g6} ^(-0.007/-0.020) |

Mounting screws
Inner hexagon bolt
+flat washer
Specification: M4*10
Material: stainless steel
Quantity: 2



Unit: mm



77B85 = Mounting spring plate(stainless steel)



↻ = Shaft rotation direction of the signal output

1) = M12 8Pin male socket

About vibration

Vibration act on encoder always cause wrong pulse, so we should pay attention to working place. More pulse per revolution, narrower groovy spacing of grating, more effect to encoder by vibration, when rev is low or stop, vibration act on shaft or main body would cause grating vibrating, so encoder might make wrong pulse.

10. Recommended Accessories

| Plug and cable | Brief description | No. | Order No. |
|--|--|--------|-----------|
|  | C2C=Connection type head A: M12, 8-pin female straight connector; Connection type head B: M12, 8-pin male straight connector; Cable length: 2M 8-core with shield,halogen-free PUR | K77C2C | 44400001 |
| | C5C=Connection type head A: M12, 8-pin female straight connector; Connection type head B: M12, 8-pin male straight connector; Cable length: 5M 8-core with shield,halogen-free PUR | K77C5C | 44400002 |
|  | C1=Connection type head A: M12, 8-pin female straight connector; Connection type head B: Bare wire end; Cable length: 1M 8-core with shield,halogen-free PUR | K77C1 | 44400003 |
| | C2=Connection type head A: M12, 8-pin female straight connector; Connection type head B: Bare wire end; Cable length: 2M 8-core with shield,halogen-free PUR | K77C2 | 44400004 |
| | C5=Connection type head A: M12, 8-pin female straight connector; Connection type head B: Bare wire end; Cable length: 5M 8-core with shield,halogen-free PUR | K77C5 | 44400005 |